

## Multi-Grid Radiative Transfer Revisited

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**Abstract.** Multi-grid radiative transfer is an efficient solution method for a variety of radiative transfer problems, in particular for problems of multiple spatial dimensions. Contrary to the commonly used operator splitting methods, the convergence rate of the multi-grid method does not deteriorate with increasing spatial resolution. It should therefore be well suited for high resolution problems.

### 1. What Is Multi-Grid Radiative Transfer and How Does It Work?

The multi-grid method is an efficient algorithm for accelerating convergence of iterative methods. The scheme alternates between an iteration that quickly reduces local (high frequency) errors, and the approximate solution on a coarse grid for reducing the global (low frequency) error. *Multi-grid radiative transfer* is the application of this scheme to radiative transfer. A good monograph on the foundations of multi-grid methods is given by Hackbusch (1985), a comprehensive web-site on multi-grid methods is maintained by Craig C. Douglas under [www.mgnet.org](http://www.mgnet.org). This paper reviews the basic method and some results of multi-grid radiative transfer.

Consider the source function,  $S(\tau) = (1 - \epsilon)J(\tau) + \epsilon B$ , with  $\epsilon$  being the thermalization parameter and  $J$  the mean intensity,  $J(\tau) = \mathbf{\Lambda}(\tau, t)S(t)$ , where  $\mathbf{\Lambda}(\tau, t)$  denotes the formal integration of the radiative transfer equation.  $B$  is the Planck function. Substitution leads to the *common  $\mathbf{\Lambda}$ -iteration*

$$S^{(n+1)} = (1 - \epsilon)\mathbf{\Lambda}S^{(n)} + \epsilon B . \quad (1)$$

Better convergence is achieved with the “*accelerated  $\mathbf{\Lambda}$ -iteration*” (*ALI*):

$$S^{(n+1)}(\tau) = [\mathbf{I} - (1 - \epsilon)\mathbf{\Lambda}^*]^{-1}(1 - \epsilon)(\mathbf{\Lambda} - \mathbf{\Lambda}^*)S^{(n)}(\tau) + \epsilon B , \quad (2)$$

where  $\mathbf{\Lambda}^*$  is a suitable approximation to  $\mathbf{\Lambda}$ .

Iterations of the type of Eq. (2) are efficient in reducing the high frequency components of the error of an intermediate solution,  $S^{(n)}(\tau)$ , (it makes the error smooth) but poorly converge with respect to the low frequency components (the overall error). The idea of the multi-grid method is to approximate this remaining smooth error on a coarse grid at accordingly low computational cost and with radiative coupling of increased scales.

Given an approximation,  $S_l^{(0)}$ , to the exact solution,  $S_l$ , on a finest level  $l$  grid. A small number (usually only one) of accelerated  $\mathbf{\Lambda}$ -iterations applied on

$S_l^{(0)}$ , the *smoothing step*, results in the intermediate solution,  $\bar{S}_l$ .  $v_l := \bar{S}_l - S_l$  is smoother than the original error,  $S_l^{(0)} - S_l$ . Defining the *defect*,  $d_l := \bar{S}_l - (1 - \epsilon)\mathbf{\Lambda}_l\bar{S}_l - \epsilon B_l$ , which is the difference between two subsequent common  $\mathbf{\Lambda}$ -iterations, we can compute the error,  $v_l$ , as:

$$v_l = (1 - \epsilon)\mathbf{\Lambda}_l v_l + d_l . \quad (3)$$

Equation (3) is of exactly the same form as the original problem, Eq. (1). But since  $v_l$  is a smooth grid function it may well be represented on a coarse grid of level  $l - 1$  with half the number of grid points of the level  $l$  grid:

$$v_{l-1} = (1 - \epsilon)\mathbf{\Lambda}_{l-1}v_{l-1} + d_{l-1} , \quad (4)$$

which is called the *coarse-grid equation*. Having computed the error on the coarse grid we *prolongate* it back to the fine grid, thus obtaining the *coarse grid correction*,  $\tilde{v}_l$ , for a new approximation to the source function:  $S_l^{\text{new}} = \bar{S}_l - \tilde{v}_l$ . Since the coarse-grid equation, Eq. (4), is of the same form as the original problem, Eq. (1), the same two-grid algorithm, described so far, can be recursively applied to Eq. (4), leading to a multi-level algorithm.

## 2. Applications

### 2.1. Homogeneous Slab of Two-Level Atoms

Figure 1 shows iterative approximations to the source function of a homogeneous slab of optical thickness  $\tau = 2000$  and a thermalization parameter  $\epsilon = 10^{-6}$ . One decade in  $\tau$  contains 6 grid points. Fig. 2a shows subsequent approximations of an accelerated  $\mathbf{\Lambda}$ -iteration with a non-local  $\mathbf{\Lambda}^*$  (nearest neighbour coupling), which have by far not converged as  $S/B$  should be  $\sqrt{\epsilon} = 10^{-3}$  at the edge of the slab. Fig. 2b shows that after only two multi-grid cycles the approximation is very close to the final solution.

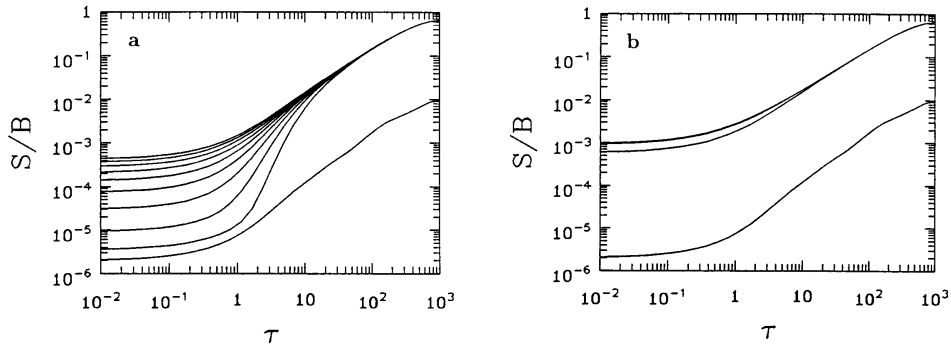


Figure 1. Subsequent approximations of the source function with **a** the non-local accelerated  $\mathbf{\Lambda}$ -iteration, **b** the multi-grid method with 3 levels. (From Steiner 1991)

## 2.2. Atmosphere in Radiative Equilibrium (RE)

The multi-grid scheme was also applied to the case of radiative transfer under the constraint of radiative equilibrium,  $B(\mathbf{r}) = J(\mathbf{r})$ , with

$$J(\mathbf{r}) = \mathbf{\Lambda}(\mathbf{r}, \mathbf{r}')B(\mathbf{r}') + G(\mathbf{r}) . \quad (5)$$

$\mathbf{r}$  is the location in a two or three-dimensional coordinate frame.  $G$  is the incident radiation from the boundaries.

Steiner (1991) considers a two-dimensional RE-problem and found the multi-grid method to be 40 times faster (in wall-clock time) than ALI. V ath (1994) applies the multi-grid method to problems of three-dimensional radiative transfer. He uses a massively parallel SIMD computer with 8192 processors.

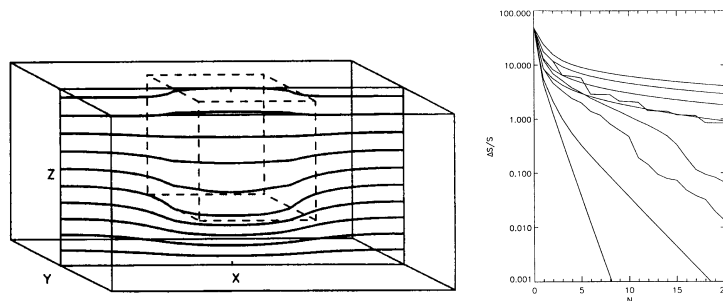


Figure 2. **Left:** Isotherms in the mid-plane of the 3-D atmosphere in RE. **Right:** Maximum relative error of the source function as function of iteration steps. From top to bottom (worst to best):  $\mathbf{\Lambda}$ -iteration, local ALI, non-local ALI, 2 level MGM, Ng acceleration, local orthomin, non-local orthomin, level 3 MGM, level 4 MGM. (From V ath 1994)

Figure 2 (left) shows the geometry and resulting isotherms. The opacity within the dashed cube is reduced to 1/5 of that in the ambient medium. Boundaries are periodic in  $x$  and  $y$ -direction. Isotropic radiation is assumed at the bottom, while no radiation is incident on the top.

Figure 2 (right) shows that the multi-grid methods with 3 and 4 levels converge smooth and fastest. However, since the computational costs of one multi-grid iteration is 2 to 7 times that of a single  $\mathbf{\Lambda}$ -iteration, the orthomin method is more efficient. This is because with massively parallel computation the CPU-time needed for a formal solution scales with  $N$ , compared with  $N^3$  in scalar mode. Also load balance is difficult to maintain. V ath (1994) concludes that multi-grid radiative transfer is not well suited for massively parallel computing.

## 2.3. Non-Linear Multigrid Radiative Transfer for Multilevel Atoms in Multi-Dimensional Space

Fabiani Bendicho, Trujillo Bueno, & Auer (1997) apply multi-grid radiative transfer to the multi-level non-LTE problem in one and two spatial dimensions. They use a Gauss-Seidel iteration scheme (MUGA) for solving the non-linear population equation and emphasize the excellent smoothing capability of

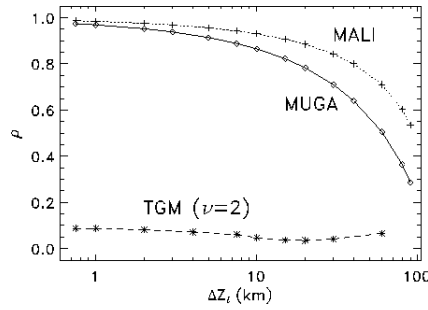


Figure 3. Contraction number for the multilevel accelerated  $\Lambda$ -iteration (MALI), the multilevel Gauss-Seidel method (MUGA), and for the two-grid method (TGM).

MUGA, making it an ideal choice for the smoothing iterations in the multi-grid method.

The *non-linear multi-grid method* differs from the linear case in that the coarse-grid equation solves for the occupation numbers,  $\mathbf{n}_{l-1}$ , directly and not just for the correction  $\Delta\mathbf{n}_{l-1}$ , and in that the restriction operator is not only applied to the residual but to the current estimate,  $\mathbf{n}_l^{\text{old}}$ , as well.

Figure 3 shows the contraction number as a function of grid spacing (in km) of three schemes for the test case of a 5-level Ca II atom in a one-dimensional (solar) atmosphere. The contraction number is basically the factor by which the error is reduced per iteration. The figure demonstrates the known and attractive property of multi-grid methods that their convergence rates are virtually independent on grid resolution, contrary to operator splitting methods that deteriorate when resolution is increased.

Balsara (2001) uses the non-linear multigrid method in conjunction with a flux conservative discretization of the radiative transfer equation in multiple spatial dimensions.

### 3. Concluding Remarks

There exists a variety of multi-grid algorithms, which might allow for further improvements of the few multi-grid radiative transfer calculations performed so far. The following bibliography is believed to be complete with respect to sources dealing with multi-grid radiative transfer.

### References

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